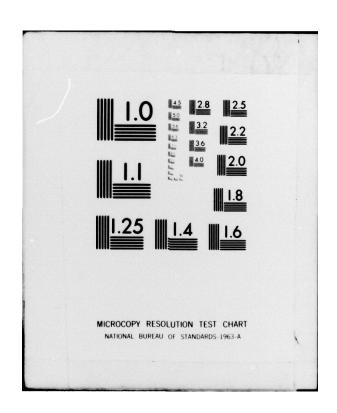
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AN IMPLICIT FUNCTION THEOREM FOR GROUP EQUATIONS
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Philip R. Thrift /
Princeton University

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1. INTRODUCTION

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mappings from a formal language L to a configuration space C. (The can be very simple or complex, depending on a particular application. reader is referred to [2] and [5] for pattern and automata theoretic jects. The algebraic nature of these operations and sets of objects notions.) In some of the cases that have been investigated, we can The study of mathematical semantics [3] involves the study of consider the set C as a set of operations G on some set of ob-In [3] these operations are called connectors when they deal with establishing or breaking relationships between these objects. automaton, C is a group G, and the semantic map apparaches thata(P) a configuration space C. In this paper we consider the study of mappings from a formal language L to of productions would then be mapped to a product of with a group element of G, p(-+ 0(p)). A sequence The study of mathematical semantics involves the special case where L = L(D), D is a finite map is observed on sentences in L(D), we discuss is defined by associating each production of D corresponding group elements. When the semantic a graph-theoretic method of solving for (8) ABSTRACT

each production p:1 \xrightarrow{X} j of D, where x E E and 1, j are states $\phi(\theta)(x_1 \ldots x_k) = \theta(p_1) \ldots \theta(p_k)$ (multiplication in G), diagram (or wiring diagram for some finite state automaton) over some alphabet E, and G (the set of operations) is a group, then we can of \mathcal{D}_{\star} If we write this map as $p \longrightarrow \theta(p) \in G_{\star}$ p a production of in the case where L = L(D), D = a deterministic finite state define a semantic map by first associating an element of G with D, then for each sentence $x_1 \, \ldots \, x_k$ in L(D), we define $s \stackrel{x_1}{\longleftarrow} i_1 \stackrel{x_2}{\longrightarrow} i_2 \dots i_{k-1} \stackrel{x_k}{\longleftarrow} i_k$ where

Pj: 1j-1 At 1 are productions of P ,

is called <u>sequential</u> if there is some map θ , $p \to \theta(p)$ p a prois a semantic map $\phi(\theta)$: L(D) \rightarrow G. A semantic map γ : L(D) \rightarrow G S = start state, and i_k ϵ final state set F of ${\cal D}$. Thus $\Phi(\theta)$ duction of θ , such that $\gamma = \phi(\theta)$.

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In this paper we consider the following problem: suppose the structure of the deterministic finite automaton $\mathcal D$ is known and we can observe $\gamma(w)$, we L($\mathcal D$). Under the assumption that γ is sequential, what can we say about all possible solutions of $\Phi(\theta) = \gamma$? The answer is stated in the form of an implicit function theorem and a procedure is given for calculating solutions.

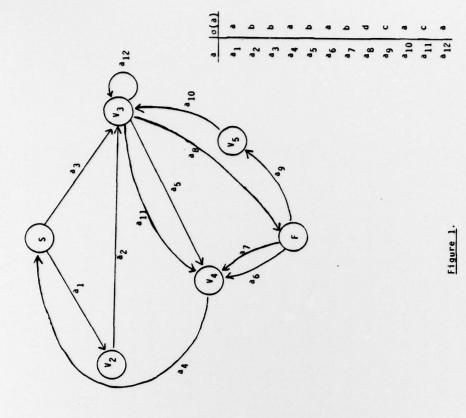
2. FINITE STATE DIAGRAMS AND GRAPH-THEORETIC NOTIONS

Let F be a directed pseudograph with <u>vertex</u> set $V(F) = \{v_1, \dots, v_p\} \qquad \text{and } \underline{arc} \text{ set}$ $A(F) = \{a_1, \dots, a_q\}. \quad (See [4] \text{ for graph-theoretic}$

(a(a_j), $\beta(a_j)$), $\alpha(a_j)$, $\beta(a_j)$ ε V(F). If $\alpha(a_j) = \beta(a_j)$ then we call a_j a loop. If Σ is some finite alphabet (a, b, c, ...) and there is a map $A(F) \xrightarrow{G} \Sigma$ satisfying the property: $\alpha(a_j) = \alpha(a_k)$, $j \neq k \xrightarrow{G} V(F)$, and if S is a single vertex of V(F), F a (non-empty) subset of V(F), then $D = (F, \Sigma, \sigma, S, F)$ is called a finite state diagram with state set V(F) and productions $\alpha(a_j) \xrightarrow{G(a_j)} B(a_j)$, $j = 1, \ldots, q$. An example appears in Figure 1 below.

In this paper we shall consider, for simplicity, only the case where F is also a single state of V(F) and $S \not= F$, so that $p = |V(F)| \ge 2$.

A finite state diagram can be used to generate sentences in E^* (that is, sequences $x_1 \dots x_k$ from E). To generate a sentence in E^* we take a <u>Malk</u> $a_1 \dots a_k$ from S to F in F (that is, a sequence of arcs such that $S = \alpha(a_1)$, $\beta(a_i) = \alpha(a_i)$)



o(a, ... a,) = o(a,) ... o(a,) by concatenation. The language generated by 0 is defined to be

L(D) = (w c ** | w = o(a1 ... a1) for some walk

a1 ... a1k from S to F).

L(D) is called a finite state language.

(unique) walk $a_1 \ldots a_k$ that generated w by using the unique-In addition, given θ , and any $w \in L(\theta)$ we can obtain the ness property of a.

apparent if a given state diagram O has a vertex v_j that does not have this property, then it can be eliminated from 0 (along with any walk a, ... a, from S to F that "passes through" vj. It is case L(D) = 4. However, we shall assume that F has the following It may happen that there are no walks from S to F, in which connectedness property: for every v_j ε $\{v_1, \ldots, v_p\}$, there is a incident arcs) and L(0) will remain the same.

Suppose we list the vertices V(F) as {S, v2, ..., vp-1, F). any vj c (v2. ... vp-1) is in Vs if there is some path from S V_{S} is defined to be the following subset of V: S ϵ V_{S} and also so that V(F) = V_S U V_F. Note that neither V_S nor V_F are ϕ Vg - (F) have the property that any path from S to Vk passes to v_j (that is, a walk from S to v_j with no vertex repeated) that does not pass through F. $V_{\rm F}$ is defined to be V(F) - $V_{\rm S}$, since S c V_S and F c V_F. Note also that elements v_k in

for any directed pseudograph f, a subgraph T is called a directed tree if:

- (a) There is exactly one vertex of T called the root which no arc of T enters.
- (b) Every vertex of T except the root has exactly one entering arc.
- (c) There is a unique path from the root to each ver-

If V(T) is the vertex set of T, then we say that T spans

We now wish to construct two directed trees in $F\colon \mathsf{T}_\mathsf{S}$ rooted

that can be reached from $v_S^{(0)}$ in a single arc. Let $A_S^{(1)}$ be a set of arcs starting from $v_{S}^{\left(0\right)}$ and having the property that every elelet $v_S^{(k)}$ be the set of vertices in $v_S - v_S^{(1)} - \dots - v_S^{(k-1)}$ that ment of $v_S^{\{1\}}$ is reached by exactly one arc of $A_S^{\{1\}}$. In general, can be reached from a vertex of $V_{\zeta}^{(k-1)}$ in a single arc, and $A_{\zeta}^{(k)}$ a set of arcs starting from $v_S^{\left(k-1\right)}$ and having the property that at S and spanning V_{S} , and T_{F} rooted at F and spanning V_{F} . $v_S^{(0)} = S$. Let $v_S^{(1)}$ be the set of all vertices in $v_S - v_S^{(0)}$ every element of $V_S^{(k)}$ is reached by exactly one arc of $A_S^{(k)}$. Continue until $V_S^{(k)}$ is empty. Let We construct T_S as follows. Start with S and define

TS = (VS) UV(1) U ..., AS1) UA(2) U ...). Clearly, TS is a tree.

Proposition. Ts spans Vs.

Let v_j E V_S. If v_j = S then we are done. Otherwise, suppose $S \xrightarrow{b_1} v_{j_1} \xrightarrow{b_2} \dots \xrightarrow{b_k} v_{j_k} = v_j$ where <Pre><Proof>.

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 v_{j_1}, \dots, v_{j_k} are also in v_{S} . Then $v_{j_1} \in v_{S}^{(0)} \cup v_{S}^{(1)}$

can be proven inductively.

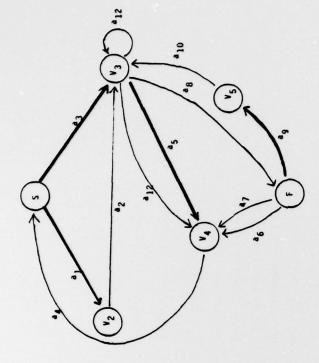
We construct $T_{\mathbf{F}}$ in exactly the same manner (substituting \mathbf{F} for \mathbf{S}).

Proposition. TF spans VF.

<Proof>. Let vk c VF. Then there is a path

where v_{k_1} $v_{k_{j-1}}$ are also in v_F , as is apparent from the definition of v_F . The proof then follows exactly as before. $\|\cdot\|$

In our previous example, we have



$$A(T_S) = \{a_1, a_3, a_5\}$$

 $A(T_F) = \{a_9\}$

Figure 2.

3. SEMANTIC MAPS AND AN IMPLICIT FUNCTION THEOREM

We now consider a group G and a map

0: A(F) + 6 .

Since there are q arcs in A(F) we shall consider θ as an element of G^q with $\theta_j=\theta(a_j)$ $j=1,\ldots,q$ called the arc values. Let Γ be the set of all semantic maps $\gamma\colon L(p)\to G$ and let

•: $6^q + \Gamma$ be defined by •(0)w = $0(a_1)$ $0(a_1)$... $0(a_1)$ if a_1 ... a_1

suppose the arcs are listed so that a_1,\ldots,a_{p-2} are the arcs in $T_S\cup T_F$, with a_{p-1},\ldots,a_q remaining. Let r=p-2 and m=q-r. We now state the following implicit function theorem.

Theorem. Assume that γ_0 c Γ is sequential. Then there exist functions $\phi_1,\ldots,\phi_m\colon G^*\to G$ (depending, of course, on γ_0) such that

(0 c 69: 0(0) = 70) =

(0 c Gq: (01, ..., 0,) c G, 0r+1 = 4, (01, ..., 0,) for 1=1,...,m).

Remark. In the case where r = 0 (that is, the case where T_S and T_F consist only of single vertices S and F) then there is a unique solution of $\Phi(\theta) = \gamma_0$.

<Proof>. By assumption there is some $\hat{\theta} \in \mathbb{G}^q$ satisfying $\theta(\hat{\theta}) = \gamma_0$. For each $(\theta_1, \ldots, \theta_r) \in \mathbb{G}^r$ we shall first show that
there exists a $(\theta_{r+1}, \ldots, \theta_q) \in \mathbb{G}^m$ such that $\Phi(\theta) = \gamma_0$, and then
show that $(\theta_{r+1}, \ldots, \theta_q)$ is uniquely determined. The uniqueness
argument gives a procedure for constructing the maps ϕ_1, \ldots, ϕ_m ,
given γ_0 .

Let v_j be an element of $v_s^{(1)}$. Then v_j appears in F as

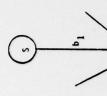


Figure 3.

with incoming arcs b_1,\ldots,b_r , loops l_1,\ldots,l_t , and outgoing arcs c_1,\ldots,c_s . Assume that b_1 is the arc that appears in T_S . Note that $\{c_1,\ldots,c_s\}$ is not empty if $A(T_S)$ is not empty. Update the arc values by the following system of assignments:

 $\hat{\theta}(b_i) \leftarrow \hat{\theta}(b_i) \hat{\theta}(b_1)^{-1} \theta(b_1)$ i = 1, ..., r $\hat{\theta}(c_j) \leftarrow \theta(b_1)^{-1} \hat{\theta}(b_1) \hat{\theta}(c_j)$ j = 1, ..., s

 $\hat{\theta}(1_k) \leftarrow \theta(b_1)^{-1} \hat{\theta}(b_1) \hat{\theta}(1_k) \hat{\theta}(b_1)^{-1} \theta(b_1) \quad k = 1, \dots, t$

Note that the arc value of b_1 is changed to $\theta(b_1)$. This operation is performed for each vertex v in $v_S^{(1)}$ and then repeated for $v_S^{(2)}$, $v_S^{(3)}$, ... until the vertex set of v_S is exhausted, and noting that once an arc value of an arc of T_S is set to the appropriate

group element, it is not changed by any subsequent update procedure.

element of G^q $\theta = (\theta_1, \dots, \theta_r, \theta_{r+1}, \dots, \theta_q)$ satisfying $\phi(\theta) = \gamma_0$. map does not change). The result of these updating procedures is an performed, the value of 4 remains the same (that is, the semantic operations. Note that after any one of these update operations is We then proceed to the vertex set V_F and perform the same

Let (g₁, ..., g_r) be the arcs entering F from V_S and (h₁,..., h_S) We now proceed to show that \$ 0r+1. 8q are unique in a concomes from a vertex in V_S, it is connected to T_S, and thus there is be the arcs entering F from V_F. Now (g₁, ..., g_r) is not empty from the assumed connectedness property satisfied by F. Since 91 structive manner. Begin at F and consider all arcs entering F. some walk a₁₁ a₁₂ ··· a_{1k} 9₁ from S to F with a₁₁ ··· a_{1k}

a path in T_S. Therefore

$$\theta(a_{1}) \cdots \theta(a_{1_{k}}) \theta(g_{1}) = \gamma_{0}(w)$$

 $\theta(g_1) = \theta(a_{i_k})^{-1} \dots \theta(a_{i_1})^{-1} \gamma_0(w)$

where w is the sentence in L(D) corresponding to a, ... a, \mathbf{g}_1 This calculation is performed for each i = 1, ..., r.

Now consider an hj. Since hj comes from a vertex in V_F, it is connected to $T_{\mathbf{f}}$, and thus there is some walk $\mathbf{b_{j}}$... $\mathbf{b_{j_1}}$ $\mathbf{h_j}$ from F to F with b_{jj} ... b_{jj} a path in T_S. Therefore

$$\theta(a_{j_1})$$
 ... $\theta(a_{j_k})$ $\theta(g_1)$ $\theta(b_{j_1})$... $\theta(b_{j_1})$ $\theta(h_j) = \gamma_0(u)$

where u is the sentence corresponding to a; ... a; 91 bj ... bj hj. We can then solve uniquely for $\theta(h_j)$.

Note that for each arc in {g₁, ..., g_r} and {h₁, ..., h_s} we provided a sentence w or u that contained that particular arc from which 0(gi), 0(hi) was recovered.

and show that $\theta(a)$ can be recovered uniquely from a single sentence. Let $C^{(j)} = \{arcs \ a \ of \ F|d(\beta(a), F) = j\}$, that is the distance (the Let us now consider any arc a which is not in A(Ts) UA(Tf) number of arcs in the shortest path) from $\beta(a_k)$ to F is j. Now (91, ..., 9r) U (h1, ..., h5) = C(0), and

 $\theta(g_1), \ldots, \theta(g_r), \theta(h_1), \ldots, \theta(h_s)$ have been computed.

induction hypothesis to solve uniquely for $\theta(a)$. In this case also, a sentence w is produced from which 0(a) is calculated. Since by a a $_{i_1}$... $_{i_j}$ be a shortest path from $\wp(a)$ to F. Now since $\alpha(a)$ the connectedness property satisfied by F, a is in one of the sets is either in $\,{\sf V}_{\sf S}\,$ or $\,{\sf V}_{\sf F}\,$ we proceed exactly as before plus use the Assume that we have computed $\theta(a)$ for arcs in $C^{(k)}$, k < j. Let a be an arc not in $A(T_S) \cup A(T_F)$ but in class $C^{\{j\}}$. Let c(0), c(1), ... ||.

4. CONCLUSION

A rather vague statement of the implicit function theorem in Euclidean space (Fleming [1]) is that

then m of the variables of x are determined implicitly $f_1(x) = 0, \dots, f_m(x) = 0$ where $x \in E^q$ and $1 \le m < q$, "if f(x) = 0 consists of m independent equations in terms of the other q - m."

Although the equation $\phi(\theta) = \gamma_0$ appears to involve an infinite number of group equations $\phi(\theta)w=\gamma_0(w)$ (one for each sentence in L(D)), if the finite set of sentences generated in the above proof

•

is M1. Wm. then the finite number of equations

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determine $\theta_{r+1} = \phi_1(\theta_1, \dots, \theta_r)$ for $l=1,\dots, m$ in the statement of the theorem. Also, any additional sentences will not reduce the solution set. In this sense, we can say that $\phi(\theta) = \gamma_0$ involves m "independent" group equations.

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